int triga=3;

int echoa=4;

int trigb=5;

int echob=6;

int trigc=7;

int echoc=8;

int pinTravelTimea;

int pinTravelTimeb;

int pinTravelTimec;

float pinTravelDistancea;

float pinTravelDistanceb;

float pinTravelDistancec;

float distanceTargeta;

float distanceTargetb;

float distanceTargetc;

int tme =5000;

int buzza=9;

int buzzb=10;

int buzzc=11;

void setup() {

  pinMode(buzza, OUTPUT);

pinMode(triga, OUTPUT);

pinMode(echoa ,INPUT);

  pinMode(buzzb, OUTPUT);

pinMode(trigb, OUTPUT);

pinMode(echob ,INPUT);

  pinMode(buzzc, OUTPUT);

pinMode(trigc, OUTPUT);

pinMode(echoc ,INPUT);

Serial. begin(9600);

}

void loop(){

digitalWrite(triga, LOW);

delayMicroseconds(10);

digitalWrite(triga, HIGH);

delayMicroseconds(10);

digitalWrite(triga, LOW);

pinTravelTimea=pulseIn(echoa, HIGH);

delay(10);

pinTravelDistancea=(pinTravelTimea\*765.\*5280.\*12)/(3600.\*1000000);

distanceTargeta=pinTravelDistancea /2;

if(distanceTargeta >20){

digitalWrite(buzza, 0);

}

if(distanceTargeta<20){

  digitalWrite(buzza, 50);

}

Serial.print("distanceTarget1 is: ");

Serial.print(distanceTargeta);

Serial.println("In.");

digitalWrite(trigb, LOW);

delayMicroseconds(10);

digitalWrite(trigb, HIGH);

delayMicroseconds(10);

digitalWrite(trigb, LOW);

pinTravelTimeb=pulseIn(echob, HIGH);

delay(10);

pinTravelDistanceb=(pinTravelTimeb\*765.\*5280.\*12)/(3600.\*1000000);

distanceTargetb=pinTravelDistanceb/2;

  if(distanceTargetb>20){

digitalWrite(buzzb, 0);

}

  if(distanceTargetb<20){

  digitalWrite(buzzb, 50);

}

Serial.print("distanceTarget2 is: ");

Serial.print(distanceTargetb);

Serial.println("In.");

digitalWrite(trigc, LOW);

delayMicroseconds(10);

digitalWrite(trigc, HIGH);

delayMicroseconds(10);

digitalWrite(trigc, LOW);

pinTravelTimec=pulseIn(echoc, HIGH);

delay(10);

pinTravelDistancec=(pinTravelTimec\*765.\*5280.\*12)/(3600.\*1000000);

distanceTargetc=pinTravelDistancec/2;

  if(distanceTargetc>20){

digitalWrite(buzzc, 0);

}

  if(distanceTargetc<20){

  digitalWrite(buzzc, 50);

}

Serial.print("distanceTarget3 is: ");

Serial.print(distanceTargetc);

Serial.println("In");

}